CMSC 35900 (Spring 2008) Learning Theory

Lecture: 2

## Perceptron and Winnow

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# **1** The Perceptron Algorithm

#### Algorithm 1 PERCEPTRON

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\begin{array}{l} w_1 \leftarrow \mathbf{0} \\ \mathbf{for} \ t = 1 \ \mathrm{to} \ T \ \mathbf{do} \\ \mathrm{Receive} \ x_t \in \mathbb{R}^d \\ \mathrm{Predict} \ \mathrm{sgn}(w_t \cdot x_t) \\ \mathrm{Receive} \ y_t \in \{-1, +1\} \\ \mathbf{if} \ \mathrm{sgn}(w_t \cdot x_t) \neq y_t \ \mathbf{then} \\ w_{t+1} \leftarrow w_t + y_t x_t \\ \mathbf{else} \\ w_{t+1} \leftarrow w_t \\ \mathbf{end} \ \mathbf{if} \\ \mathbf{end} \ \mathbf{for} \end{array}
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The following theorem gives a dimension independent bound on the number of mistakes the PERCEPTRON algorithm makes.

Theorem 1.1. Suppose Assumption M holds. Let

$$M_T := \sum_{t=1}^T \mathbf{1} \left[ \operatorname{sgn}(w_t \cdot x_t) \neq y_t \right]$$

denote the number of mistakes the PERCEPTRON algorithm makes. Then we have,

$$M_T \le \frac{\|x_{1:T}\|^2 \cdot \|w^*\|^2}{\gamma^2}$$

*Proof.* The key idea of the proof is to look at how the quantity  $w^* \cdot w_t$  evolves over time. We first provide an lower bound for it. Define  $m_t = \mathbf{1} [\operatorname{sgn}(w_t \cdot x_t) \neq y_t]$ . Note that  $w_{t+1} = w_t + y_t x_t m_t$  and  $M_T = \sum_t m_t$ . We have,

$$w^* \cdot w_{t+1} = w^* \cdot w_t + y_t x_t m_t$$
  
=  $w^* \cdot w_t + y_t (w^* \cdot x_t) m_t$   
 $\geq w^* \cdot w_t + \gamma m_t$ . (Assumption M)

Unwinding the recursion, we get

$$w^* \cdot w_{T+1} \ge w^* \cdot w_1 + \gamma M_T = \gamma M_T . \tag{1}$$

Now, we use Cauchy-Schwarz inequality to get the upper bound,

$$w^* \cdot w_{T+1} \le \|w^*\| \cdot \|w_{T+1}\| \,. \tag{2}$$

Moreover,

$$||w_{t+1}||^2 = ||w_t + y_t x_t m_t||^2$$
  
=  $||w_t||^2 + 2y_t (w_t \cdot x_t) m_t + ||x_t||^2 m_t$   
 $\leq ||w_t||^2 + 0 + ||x_{1:T}||^2 m_t$ ,

where the last step follows because  $y_t(w_t \cdot x_t) < 0$  when a mistake is made and  $||x_t|| \le ||x_{1:T}||$ . Unwinding the recursion once again, we get,

$$||w_{T+1}||^2 \le ||w_1||^2 + ||x_{1:T}||^2 M_T = ||x_{1:T}||^2 M_T.$$
(3)

Combining (1), (2) and (3) gives,

$$\gamma M_T \le w^* \cdot w_{T+1} \le \|w^*\| \cdot \|w_{T+1}\| \le \|w^*\| \cdot \|x_{1:T}\| \sqrt{M_T} .$$
$$T_T \le \|w^*\|^2 \cdot \|x_{1:T}\|^2 / \gamma^2.$$

This implies that  $M_T \le ||w^*||^2 \cdot ||x_{1:T}||^2 / \gamma^2$ .

### 2 Lower Bound

**Theorem 2.1.** Suppose  $\mathcal{X} = \{x \in \mathbb{R}^d \mid ||x|| \le 1\}$  and  $\frac{1}{\gamma^2} \le d$ . Then for any deterministic algorithm, there exists a data set which is separable by a margin of  $\gamma$  on which the algorithm makes at least  $\lfloor \frac{1}{\gamma^2} \rfloor$  mistakes.

*Proof.* Let  $n = \lfloor \frac{1}{\gamma^2} \rfloor$ . Note that  $n \le d$  and  $\gamma^2 n \le 1$ . Let  $\mathbf{e}_i$  be the unit vector with a 1 in the *i*th coordinate and zeroes in others. Consider  $\mathbf{e}_1, \ldots, \mathbf{e}_n$ . We now claim that, for any  $b \in \{-1, +1\}^n$ , there is a w with  $||w|| \le 1$  such that

$$\forall i \in [n], \ b_i(w_i \cdot \mathbf{e}_i) = \gamma \ .$$

To see this, simply choose  $w_i = \gamma b_i$ . Then the above equality is true. Moreover,  $||w||^2 = \gamma^2 \sum_{i=1}^n b_i^2 = \gamma^2 n \le 1$ .

Now given an algorithm  $\mathcal{A}$ , define the data set  $\{(x_i, y_i)\}_{i=1}^n$  as follows. Let  $x_i = \mathbf{e}_i$  for all i and  $y_1 = -\mathcal{A}(x_1)$ . Define  $y_i$  for i > 1 recursively as

$$y_i = -\mathcal{A}(x_1, y_1, \dots, x_{i-1}, y_{i-1}, x_i)$$
.

It is clear that the algorithm makes n mistakes when run on this data set. By the above claim, no matter what  $y_i$ 's turn out to be, the data set is separable by a margin of  $\gamma$ .

### **3** The Winnow Algorithm

Input parameter:  $\eta > 0$  (learning rate)

#### Algorithm 2 WINNOW

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\begin{split} w_{1} \leftarrow \frac{1}{d} \mathbf{1} \\ \text{for } t &= 1 \text{ to } T \text{ do} \\ \text{Receive } x_{t} \in \mathbb{R}^{d} \\ \text{Predict } \operatorname{sgn}(w_{t} \cdot x_{t}) \\ \text{Receive } y_{t} \in \{-1, +1\} \\ \text{if } \operatorname{sgn}(w_{t} \cdot x_{t}) \neq y_{t} \text{ then} \\ \forall i \in [d], w_{t+1,i} \leftarrow \frac{w_{t,i} \exp(\eta y_{t} x_{t,i})}{Z_{t}} \text{ where } Z_{t} = \sum_{i=1}^{d} w_{t,i} \exp(\eta y_{t} x_{t,i}) \\ \text{else} \\ w_{t+1} \leftarrow w_{t} \\ \text{end if} \\ \text{end for} \end{split}
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**Theorem 3.1.** Suppose Assumption M holds. Further assume that  $w^* \ge 0$ . Let

$$M_T := \sum_{t=1}^T \mathbf{1} \left[ \operatorname{sgn}(w_t \cdot x_t) \neq y_t \right]$$

denote the number of mistakes the WINNOW algorithm makes. Then, for a suitable choice of  $\eta$ , we have,

$$M_T \le \frac{2\|x_{1:T}\|_{\infty}^2 \cdot \|w^*\|_1^2}{\gamma^2} \ln d$$

*Proof.* Let  $u^* = w^*/||w^*||$ . Since we assume  $w^* \ge 0$ ,  $u^*$  is a probability distribution. At all times, the weight vector  $w_t$  maintained by WINNOW is also a probability distribution. Let us measure the progress of the algorithm by analyzing the *relative entropy* between these two distributions at time t. Accordingly, define

$$\Phi_t := \sum_{i=1}^d u_i^* \ln \frac{u_i^*}{w_{t,i}} \, .$$

When there is no mistake  $\Phi_{t+1} = \Phi_t$ . On a round when a mistake occurs, we have

$$\Phi_{t+1} - \Phi_t = \sum_{i=1}^d u_i^* \ln \frac{w_{t,i}}{w_{t+1,i}}$$
  
=  $\sum_{i=1}^d u_i^* \ln \frac{Z_t}{\exp(\eta y_t x_{t,i})}$   
=  $\ln(Z_t) \sum_{i=t}^d u_i^* - \eta y_t \sum_{i=1}^d u_i^* x_{t,i}$   
=  $\ln(Z_t) - \eta y_t (u^* \cdot x_t)$   
 $\leq \ln(Z_t) - \eta \gamma / \|w^*\|_1$ , (4)

where the last inequality follows from the definition of  $u^*$  and Assumption M. Let  $L = ||x_{1:T}||_{\infty}$ . Then  $y_t x_{t,i} \in [-L, L]$  for all t, i. Then we can bound

$$Z_t = \sum_{i=1}^d w_{t,i} e^{\eta y_t x_{t,i}}$$

using the convexity of the function  $t \mapsto e^{\eta t}$  on the interval [-L, L] as follows.

$$\begin{split} Z_t &\leq \sum_{i=1}^d \frac{1 + y_t x_{t,i}/L}{2} e^{\eta L} + \frac{1 - y_t x_{t,i}/L}{2} e^{-\eta L} \\ &= \frac{e^{\eta L} + e^{-\eta L}}{2} \sum_{i=1}^d w_{t,i} + \frac{e^{\eta L} - e^{-\eta L}}{2} \left( y_t \sum_{i=1}^d w_{t,i} x_{t,i} \right) \\ &= \frac{e^{\eta L} + e^{-\eta L}}{2} + \frac{e^{\eta L} - e^{-\eta L}}{2} y_t(w_t \cdot x_t) \\ &\leq \frac{e^{\eta L} + e^{-\eta L}}{2} \end{split}$$

because having a mistake implies  $y_t(w_t \cdot x_t) \leq 0$  and  $e^{\eta L} - e^{-\eta L} > 0$ . So we have proved

$$\ln(Z_t) \le \ln\left(\frac{e^{\eta L} + e^{-\eta L}}{2}\right) \,. \tag{5}$$

Define

$$C(\eta) := \eta \gamma / \|w^*\|_1 - \ln\left(\frac{e^{\eta L} + e^{-\eta L}}{2}\right) .$$

Combining (4) and (5) then gives us

$$\Phi_{t+1} - \Phi_t \le -C(\eta)\mathbf{1} \left[ y_t \neq \operatorname{sgn}(w_t \cdot x_t) \right] \,.$$

Unwinding the recursion gives,

$$\Phi_{T+1} \leq \Phi_1 - C(\eta) M_T \; .$$

Since relative entropy is always non-negative  $\Phi_{T+1} \ge 0$ . Further,

$$\Phi_1 = \sum_{i=1}^d u_i^* \ln(du_i^*) \le \sum_{i=1}^d u_i^* \ln d = \ln d$$

which gives us

$$0 \le \ln d - C(\eta)M_T$$

and therefore  $M_T \leq \frac{\ln d}{C(\eta)}$ . Setting

$$\eta = \frac{1}{2L} \ln \left( \frac{L + \gamma / \|w^*\|_1}{L - \gamma / \|w^*\|_1} \right)$$

to maximize the denominator  $C(\eta)$  gives

$$M_T \le \frac{\ln d}{g\left(\frac{\gamma}{L\|w^*\|_1}\right)}$$

where  $g(\epsilon) := \frac{1+\epsilon}{2} \ln(1+\epsilon) + \frac{1-\epsilon}{2} \ln(1-\epsilon)$ . Finally, noting that  $g(\epsilon) \ge \epsilon^2/2$  proves the theorem.