# Near-optimal distortion bounds for embedding doubling spaces into L<sub>1</sub>

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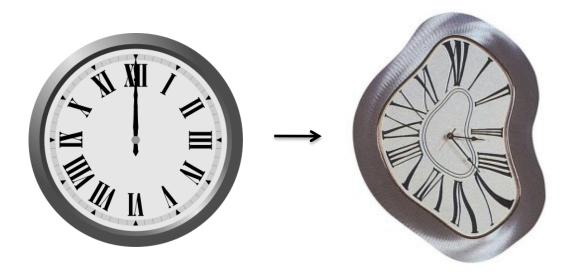
Joint work with James R. Lee (U. Washington)

### Metric embeddings

- Given spaces M=(X,d), M'=(X',d')
- Mapping f : X→X'
- Distortion c if:

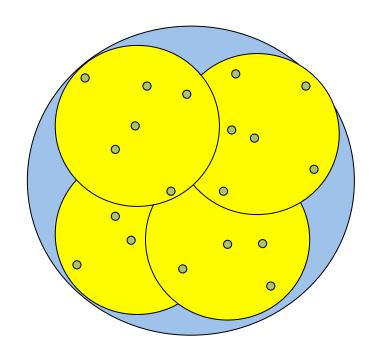
$$d(x_1,x_2) \le d'(f(x_1),f(x_2)) \le c \cdot d(x_1,x_2)$$

•  $c_{Y}(X)$  = infimum distortion to embed X into Y



### Doubling spaces

- A metric (X, d) is doubling if every ball of radius r can be covered by O(1) balls of radius r/2.
- Metric notion of "bounded dimension"



# Distortion of L<sub>1</sub> embeddings

- n-point metrics: O(log n) [Bourgain '85]
- n-vertex expanders: Ω(log n)
   [Linial, London, Rabinovich '95]
- Doubling metrics : O(log n)<sup>1/2</sup>
   [Gupta,Krauthgamer,Lee '03]
- Doubling metrics :  $\Omega(\log n)^{\delta}$ , for some  $\delta > 0$  [Cheeger, Kleiner, Naor '09]

#### Our result

#### Theorem [Lee,S '11]

There exists an infinite family of uniformly doubling spaces that require distortion

$$\Omega\left(\sqrt{\frac{\log n}{\log\log n}}\right)$$

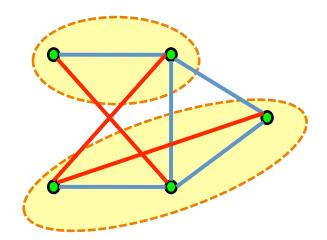
to be embedded into  $L_1$ .

I.e. matching the upper bound of Gupta-Krauthgamer-Lee up to a  $O((\log \log n)^{1/2})$  factor.

### **Sparsest-Cut**

#### Instance:

- G = (V,E)
- cap :  $V \times V \rightarrow R$
- dem: V×V→R



sparsity of a cut S = (capacity in S) / (demand crossing S)

#### Key step for a plethora of divide & conquer algorithms:

Crossing Number, Linear Arrangement, VLSI layout, Feedback Arc Set, Balanced Cut, Directed Cuts, Multi-way Cut, Scheduling, PRAM Emulation, Routing, Interval Graph Completion, Planar Edge Deletion, Pathwidth, Markov Chains, ... [Leighton, Rao '99], ...

### Approximating the Sparsest-Cut

- O(log n)-approximation [Linial, London, Rabinovich'95], [Leighton, Rao'88]
- O(log<sup>1/2</sup> n loglog n)-approximation [Arora,Lee,Naor'05], [Arora,Rao,Vazirani'04]
- 1.001-hard [Ambuhl, Mastrolilli, Svensson'07]
- ω(1)-hard assuming Unique Games [Khot, Vishnoi '05],
   [Chawla, Krauthgamer, Kumar, Rabani, Sivakumar '05]

### Negative type

(X,d) is in **NEG** if  $c_2(X,d^{1/2}) = 1$ 

(X,d) is in **soft-NEG** if  $c_2(X,d^{1/2}) = O(1)$ 

# The geometry of graphs

SDP relaxation: O(log<sup>1/2</sup> n loglog n)-approximation [Arora,Lee,Naor'05], [Chawla,Gupta,Racke'05], [Arora,Rao,Vazirani'04]

#### Theorem:

SDP integrality gap = min distortion to embed any n-point negative-type metric into  $L_1$ .

Theorem: [Arora,Lee,Naor'05]

Every n-point negative-type metric embeds into  $L_1$  with distortion  $O(log^{1/2} n loglog n)$ .

# NEG vs L<sub>1</sub>

#### Major open question:

What is the integrality gap of the Sparsest-Cut SDP?

#### **Equivalently:**

What is the worst-case distortion required to embed a negative-type metric into  $L_1$ ?

### The Goemans-Linial conjecture

#### Conjecture [Goemans, Linial'94]

Every negative-type metric embeds into  $L_1$  with distortion O(1).

#### **Theorem** [Khot, Vishnoi'05]

There exist an n-point negative-type metric that requires distortion  $\Omega(\log\log n)^c$  to embed into L<sub>1</sub>.

(see also [Krauthgamer, Rabani], [Devanur, Khot, Saket, Vishnoi])

## The Heisenberg group

#### Theorem [Lee, Naor'06]

The Heisenberg group H<sup>3</sup>(R), with the Carnot-Caratheodory metric is in NEG.

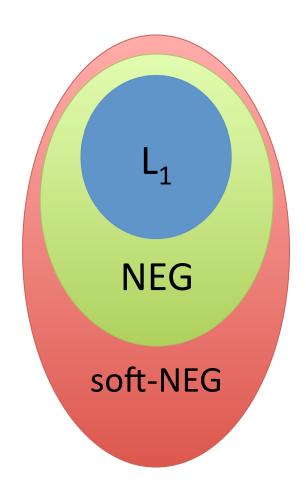
**Theorem** [Cheeger, Kleiner, Naor'09], [Cheeger, Kleiner'06]  $H^3(R)$  requires distortion  $\Omega((\log n)^c)$ , for some c>0, to embed into  $L_1$ .

#### **Corollary**

The integrality gap of the Sparsest-Cut SDP is  $\Omega((\log n)^c)$ , for some c>0.

## Soft negative-type

- All known algorithms for Sparsest-Cut require only soft-NEG
- This fact is essential for some fast algorithms [Sherman'09]



### Our result

#### Theorem [Lee,S '11]

There exists a doubling space that requires distortion

$$\Omega\left(\sqrt{\frac{\log n}{\log\log n}}\right)$$

to be embedded into  $L_1$ .

#### Theorem [Assouad'83]

Every doubling space is in soft-NEG.

#### Corollary [Lee,S '11]

There exists a metric in soft-NEG that requires distortion

$$\Omega\left(\sqrt{\frac{\log n}{\log\log n}}\right)$$

to be embedded into  $L_1$ .

### In other words...

#### Corollary [Lee, S '11]

Every known upper bound analysis of the Sparsest-Cut SDP, is tight up to (loglog n)<sup>O(1)</sup> factors.

### Main result

Sparsest-cut SDP:

$$\min \left\{ \frac{\sum_{u,v} cap(u,v) \|x_u - x_v\|_2^2}{\sum_{u,v} dem(u,v) \|x_u - x_v\|_2^2} : (\{x_v\}_v, \|\|_2^2) \in NEG \right\}$$

Sparsest-cut weak SDP:

$$\min \left\{ \frac{\sum_{u,v} cap(u,v) \|x_u - x_v\|_2^2}{\sum_{u,v} dem(u,v) \|x_u - x_v\|_2^2} : (\{x_v\}_v, \|\|_2^2) \in soft - NEG \right\}$$

**Corollary** [Lee,S]

The integrality gap of the weak SDP is  $\Theta((\log n)^{1/2})$ , up to  $(\log \log n)^{O(1)}$  factors.

Improves over the previous bound of  $\Omega(\log n)^{1/4}$  [Lee, Moharrami' 10]

# Key ingredients of the proof

A new topological construction of a hard space

Discrete differentiation

Discrete/approximate integral geometry in the plane

# The Gupta-Newman-Rabinovich-Sinclair conjecture

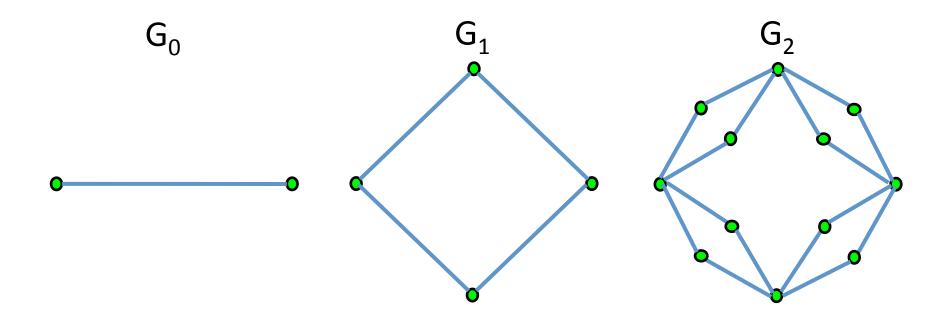
Conjecture [Gupta, Newman, Rabinovich, Sinclail '99]

Every minor-free family of graph embeds into  $L_1$  with distortion O(1).

#### True for:

- Trees
- Series-parallel graphs [Gupta, Newman, Rabinovich, Sinclail '99]
- O(1)-Outerplanar graphs [Chekuri, Gupta, Newman, Rabinovich, Sinclair '2003]
- O(1)-pathwidth graphs [Lee, S '2009]
- (K<sub>5</sub>\e)-free graphs [Chakrabarti, Jaffe, Lee, Vincent '2008]

# The diamond graph



## Embedding the diamond graph

Theorem [Rao '99], [Newman, Rabinovich '2002]

$$c_2(\text{diamond graph}) = \Theta(\sqrt{\log n})$$

**Theorem** [Gupta, Newman, Rabinovich, Sinclail '99], [Chakrabarti, Jaffe, Lee, Vincent '2008]

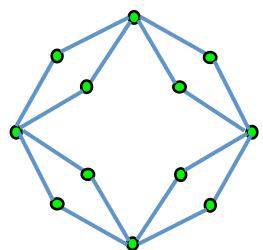
$$c_1(\text{diamond graph}) \leq 2$$

# Embedding the diamond graph

• In L<sub>2</sub>, there is always a diagonal that incurs unbounded contraction.

[Newman, Rabinovich' 2002]

• Why not in  $L_1$ ?



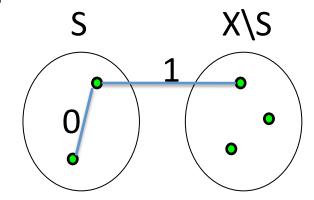
# A combinatorial interpretation of L<sub>1</sub>

An embedding into  $L_1$  is a distribution over cuts

### The cut cone

• For a finite set X, and  $S \subseteq X$ , let

$$d_S: X \times X \longrightarrow R,$$
  
 $d_S(x,y) = |\mathbf{1}_S(x) - \mathbf{1}_S(y)|$ 



• A mapping  $d: X \times X \to R$  is in the **cut cone** if there exists a non-negative measure  $\mu$  on  $2^X$ , s.t.

$$\forall x, y \in X, d(x, y) = \int d_S(x, y) d\mu(S)$$

#### Fact:

A metric is isometrically embeddable into  $L_1$ , if and only if it is in the cut cone.

# L<sub>1</sub> and the cut cone: example

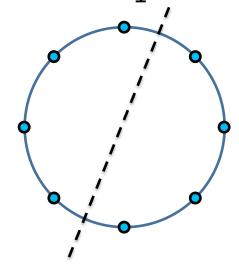
Embed the n-line into L<sub>1</sub>

Pick random x in  $\{1,...,n-1\}$ , and take the cut  $\{1,...,x\}$ 



Embed the n-cycle into L<sub>1</sub>

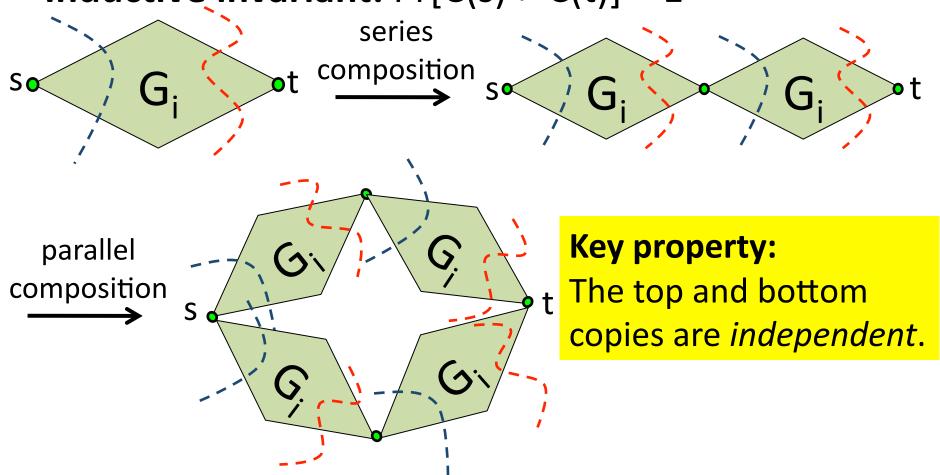
Pick random angle



## Embedding the diamond graph into L<sub>1</sub>

[Gupta, Newman, Rabinovich, Sinclail '99]

**Inductive invariant:**  $Pr[C(s) \neq C(t)] = 1$ 



#### Towards a construction

Can we inductively construct a "simple" space s.t. the random cuts in smaller copies are not independent?

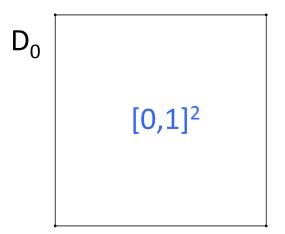
k-Sums Conjecture [Lee, S '09]

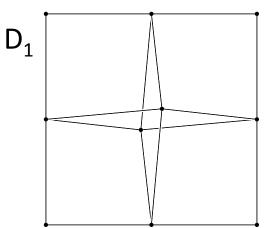
O(1)-Embeddability into L₁ is closed under k-sums.

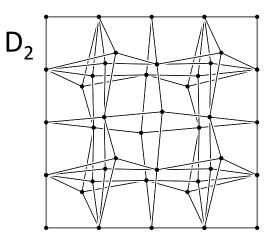
We need a *qualitatively* different inductive construction.

### The new construction

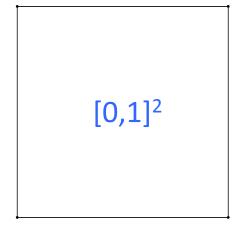
#### The diamond-fold

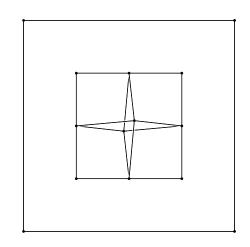


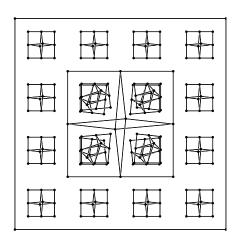




#### The Laakso-fold







# Differentiation of L<sub>1</sub>-valued maps

 [Cheeger, Kleiner'06] develop a weak differentiation theory for maps into L<sub>1</sub>.

• [Cheeger, Kleiner'09], [Lee, Raghaventra'07] Main idea: At a sufficiently small scale, almost all cuts are "well-structured".

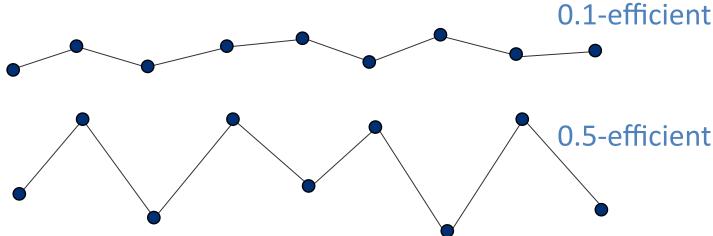
#### Coarse differentiation

#### [Matousek'99], [Eskin, Fisher, Whyte'06]

Let (Y,d) be any metric space,  $\varepsilon$ >0

f:P<sub>n</sub> $\rightarrow$ Y, is  $\epsilon$ -efficient if

$$\sum_{i=1}^{n-1} d(f(x_i), f(x_{i+1})) \le (1+\varepsilon)d(x_1, x_n)$$



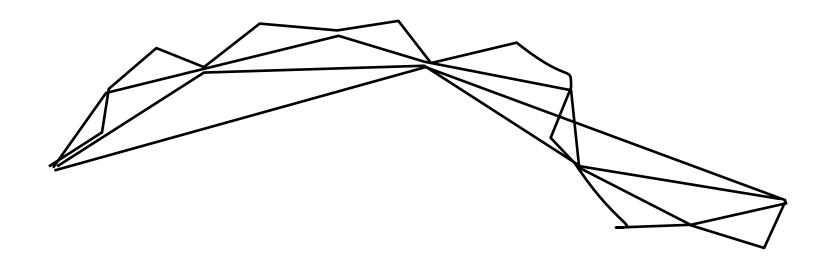
# Coarse differentiation (toy version)

Theorem [Matousek'99], [Eskin, Fisher, Whyte'06] Let (Y,d) be any metric space, D>0. For any  $\varepsilon$ >0 (arbitrarily small), there exists n>0, such that for any  $f:P_n \longrightarrow Y$  with distortion D, we can find an  $\varepsilon$ -efficient copy of  $P_3$  in  $f(P_n)$ .

### Coarse differentiation

#### **Proof idea:**

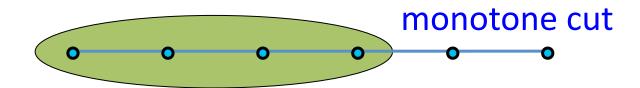
Suppose *no* scale is  $\varepsilon$ -efficient.

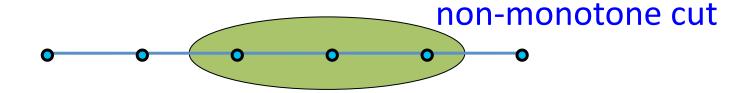


# Differentiation in L<sub>1</sub>

#### [Lee, Raghaventra'07], [Cheeger, Kleiner'09]

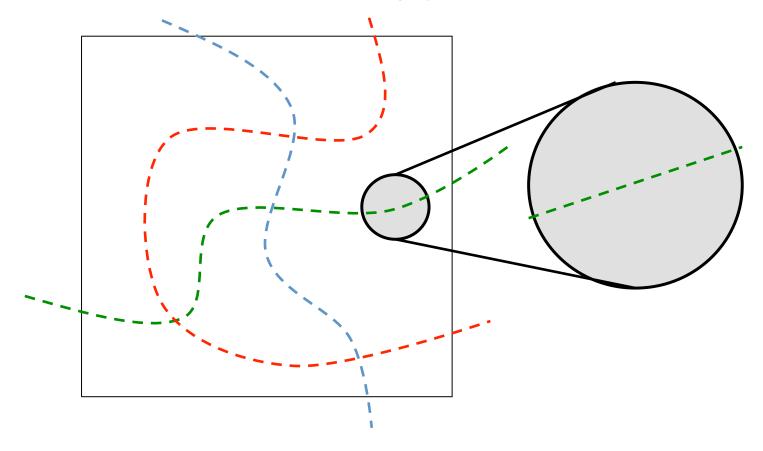
f :  $P_n \rightarrow L_1$  is 0-efficient if and only if all cuts are half-lines.





# Differentiation for maps $[0,1]^2 \rightarrow L_1$

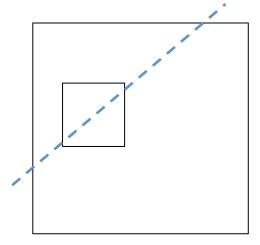
Locally, the distribution of cuts consists mostly of (near-)half-planes.

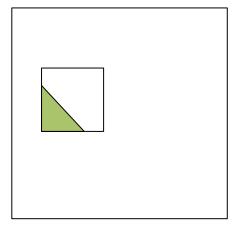


#### Differentiation and the diamond-fold

#### Main idea:

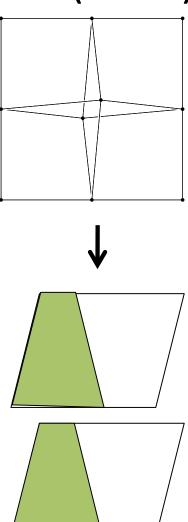
- Let f:  $[0,1]^2 \to L_1$
- Then, at a sufficiently small square X, for every line h intersecting X, almost all cuts restricted on h, are half-lines.
- Suppose that all cuts restricted to every line are half-lines.
   Then, all cuts are half-planes.



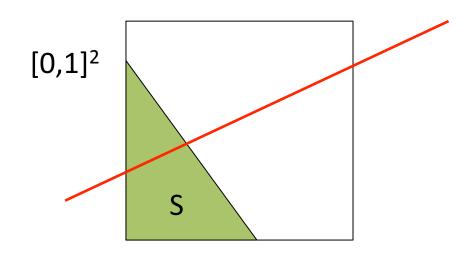


### Differentiation and the diamond-fold (cont.)

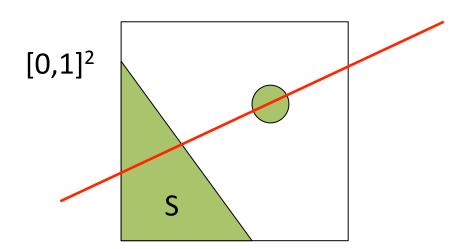
- It follows that there exists a copy of  $D_1$ , such that in both copies of  $[0,1]^2$ , all cuts are half-planes.
- But then the half-planes must be identical in both sheets.
- Thus, the two sheets are collapsed.



#### Differentiation and the diamond-fold



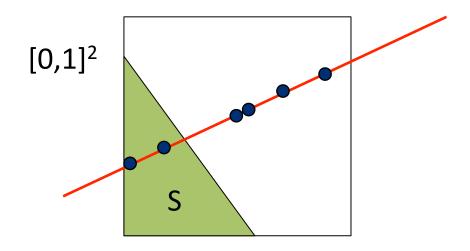
A map is 0-efficient if and only if every cut is a halfplane



Obstacle: An ε-efficient map might have **no** halfplane cuts

### The quantitative bound

- We define efficiency w.r.t. **random** lines in the unit square.
- Avoid periodicities: define efficiency w.r.to a random subset of points in every line.



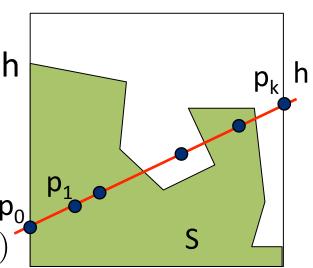
### Taming ε-efficient maps

- Pick random line h
- Pick random set P of  $k=1/\epsilon^{O(1)}$  points in h
- $p_0$ ,  $p_k$  are on the boundary
- "Complexity" of a set:

$$C^*(S) = \int \mathbb{E}_P \sum_j |\mathbf{1}_S(p_j) - \mathbf{1}_S(p_{j+1})| d\mu(h)$$

$$C(S) = \int \mathbb{E}_P |\mathbf{1}_S(p_0) - \mathbf{1}_S(p_k)| d\mu(h)$$

Fact:  $C^*(S) = C(S)$  iff S is a half-plane



# Taming ε-efficient maps (cont.)

#### Lemma: [Lee,S]

If 
$$|C^*(S) - C(S)| = O(\varepsilon^2)$$
,

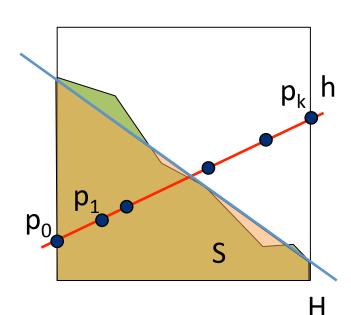
then there exists half-plane H, such that

$$|S \triangle (H \cap [0,1]^2)| = O(\varepsilon)$$



If  $|C^*(S) - C(S)| = O(\epsilon^2)$ , and |S| < 1/16, then there exists half-plane H, such that

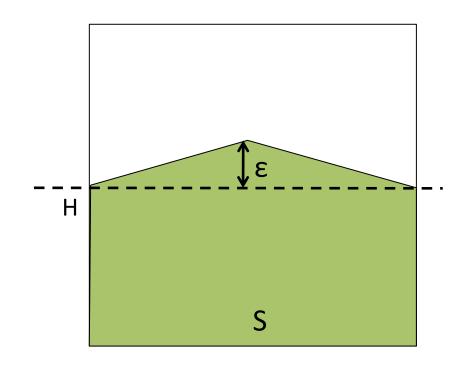
$$\left| (S \triangle H) \cap \left[ \frac{1}{3}, \frac{3}{4} \right]^2 \right| = O(\varepsilon^2)$$



# Tightness of the analysis

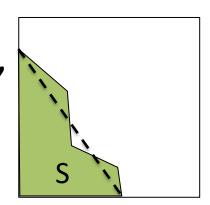
$$|(S \triangle H) \cap [0,1]^2| = O(\varepsilon)$$

$$|C(S) - C^*(S)| = O(\varepsilon^2)$$

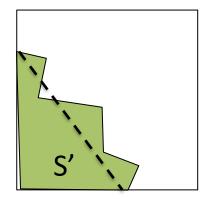


## Obtaining the distortion bound

Consider two parallel "sheets"
Since the boundaries are identified,
both S and S' are close to the
same half-plane.

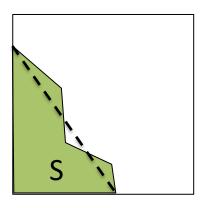


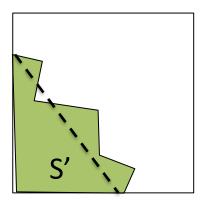
Thus, S and S' are close to each other.



### Obtaining the distortion bound (cont.)

If S and S' are close to each other, then the distance between most antipodals that are close to the center of [0,1]<sup>2</sup>, is too small!





#### Further directions

- NEG vs L<sub>1</sub>?
- Can these techniques be used to obtain computational hardness?
- Gupta-Newman-Rabinovich-Sinclair conjecture: Minor-free graphs into L<sub>1</sub>? The diamondfold contains arbitrarily large clique minors.