

Action Recognition Using a Distributed Representation of Pose and Appearance*

Adobe

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Motivation: Human Ability to Recognize the Pose and Action from Limited Views



Action and pose is revealed by body parts at various scales and locations

Robust Representation of Pose and Appearance

Poselet Activation Vector



top 9 poselets

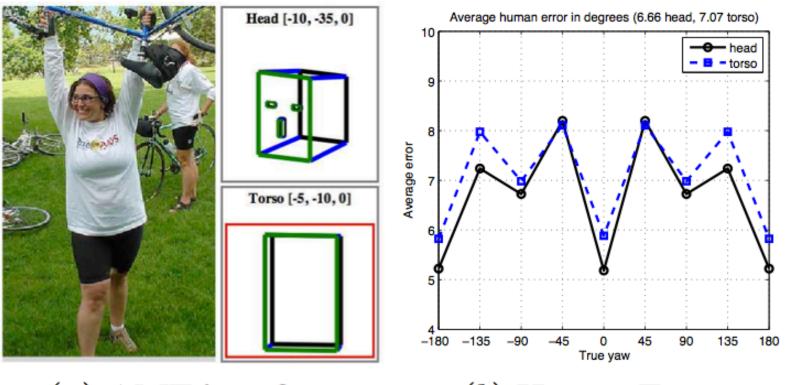




top 9 poselets

Represent each example by the poselets that are active. Provides a distributed representation of pose and appearance

Collecting Annotations on AMT



(a) AMT interface (b) Human Error 3d pose of head and torso, joint locations on PASCAL VOC 10 images

Poselets of People^[1]

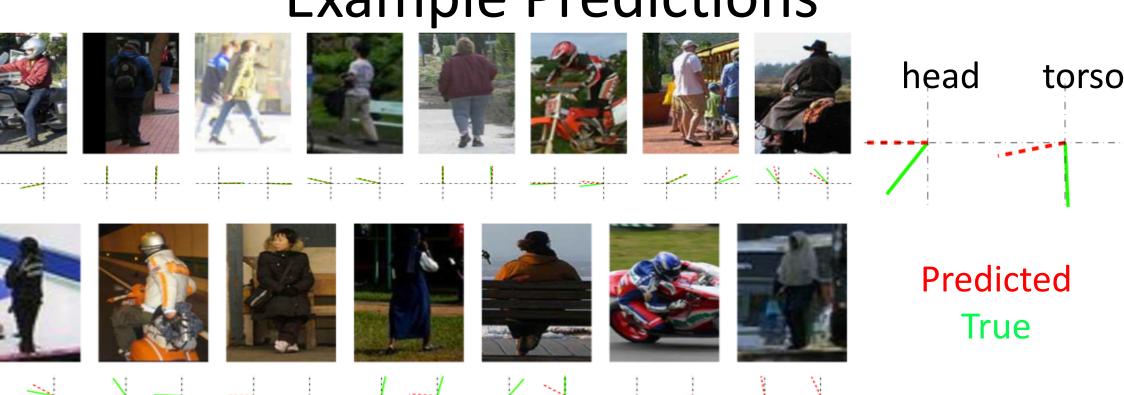




Selected poselets for pose estimation.

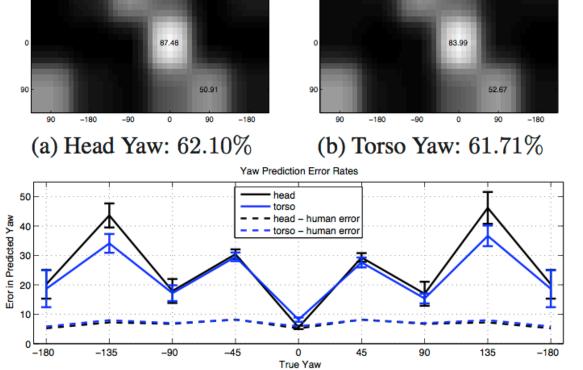
Information is combined from various scales and locations

Example Predictions



Discrete pose prediction accuracy

Top 100 poselets



Yaw prediction error View Bango Hoad Torco

неаа	iorso
26.3°	23.4°
20.0°	19.6°
5.1°	6.5°
	26.3° 20.0°

Matches human performance

Action Specific Pose and Appearance



Top 36 training examples

less

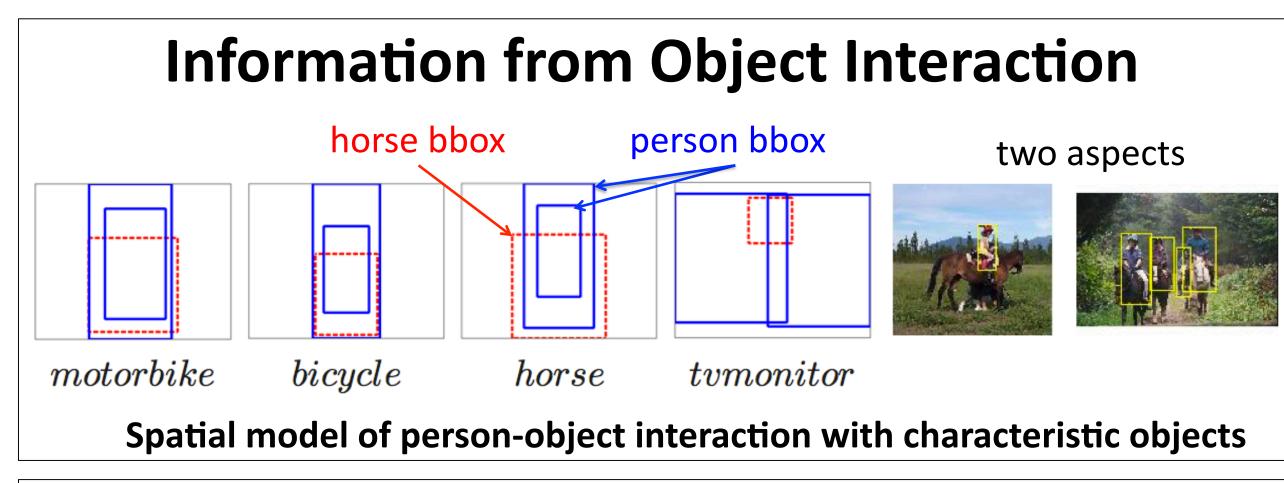
discriminative

Pose. Select the poselets that capture salient pose. The top poselet is more discriminative as its similar examples contain more Instances from within the same category.

Appearance. Restrict training examples from within the same category.

Selected Poselets for Action Classification

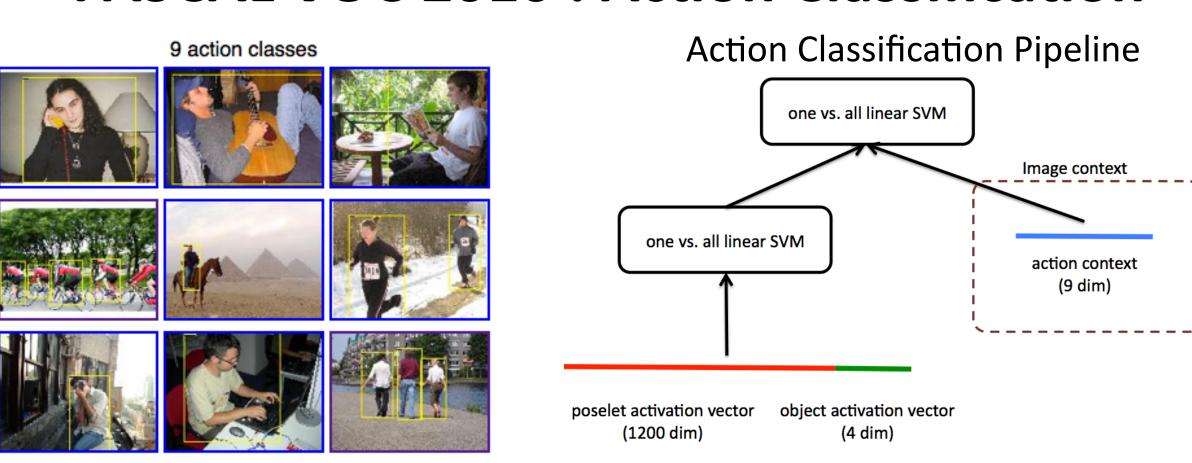




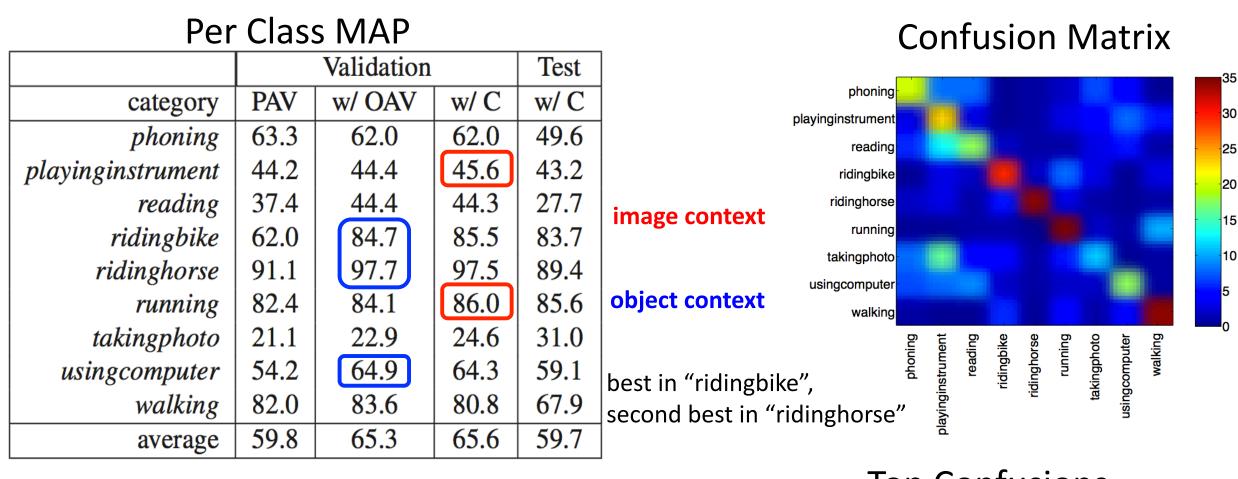


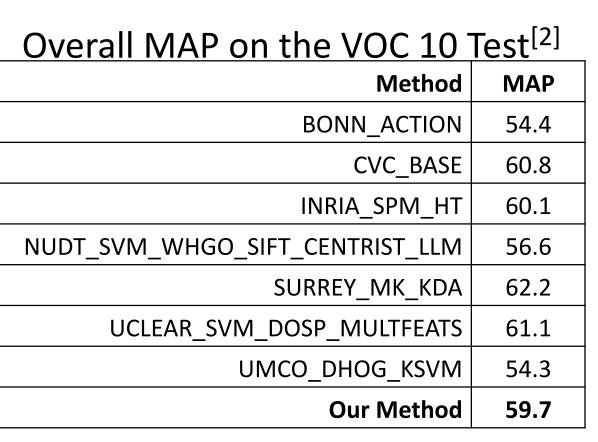
Group activities. Information from the actions of others agents in an image.





Action Classification Results (MAP)







References

[1] L.Bourdev, S.Maji, T.Brox and J. Malik, Detecting People using Mutually Consistent Poselet Activations, ECCV 2010

[2] http://pascallin.ecs.soton.ac.uk/challenges/VOC/voc2010/results/index.html Pose estimation: www.cs.berkeley.edu/~smaji/projects/3dpose

Action classification: www.cs.berkeley.edu/~smaji/projects/action