

Lecture 3: October 4, 2016

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1 Linear Transformations

Definition 1.1 Let V and W be vector spaces over the same field \mathbb{F} . A map $\varphi : V \rightarrow W$ is called a linear transformation if

- $\varphi(v_1 + v_2) = \varphi(v_1) + \varphi(v_2) \quad \forall v_1, v_2 \in V.$
- $\varphi(c \cdot v) = c \cdot \varphi(v) \quad \forall v \in V.$

Example 1.2 The following are all linear transformations:

- A matrix $A \in \mathbb{R}^{m \times n}$ defines a linear transformation from \mathbb{R}^n to \mathbb{R}^m .
- $\varphi : C([0, 1], \mathbb{R}) \rightarrow C([0, 2], \mathbb{R})$ defined by $\varphi(f)(x) = f(x/2)$.
- $\varphi : C([0, 1], \mathbb{R}) \rightarrow C([0, 1], \mathbb{R})$ defined by $\varphi(f)(x) = f(x^2)$.
- $\varphi : C([0, 1], \mathbb{R}) \rightarrow C([0, 1], \mathbb{R})$ defined by $\varphi(f)(x) = f(1 - x)$.
- $\varphi_{\text{left}} : \mathbb{R}^{\mathbb{N}} \rightarrow \mathbb{R}^{\mathbb{N}}$ defined by $\varphi_{\text{left}}(f)(n) = f(n + 1)$.
- The derivative operator acting on $\mathbb{R}[x]$.

Proposition 1.3 Let V, W be vector spaces over \mathbb{F} and let B be a basis for V . Let $\alpha : B \rightarrow W$ be an arbitrary map. Then there exists a unique linear transformation $\varphi : V \rightarrow W$ satisfying $\varphi(v) = \alpha(v) \quad \forall v \in B$.

Definition 1.4 Let $\varphi : V \rightarrow W$ be a linear transformation. We define its kernel and image as:

- $\ker(\varphi) := \{v \in V \mid \varphi(v) = 0_W\}.$
- $\text{im}(\varphi) = \{\varphi(v) \mid v \in V\}.$

Proposition 1.5 $\ker(\varphi)$ is a subspace of V and $\text{im}(\varphi)$ is a subspace of W .

Proposition 1.6 (rank-nullity theorem) *If V is a finite dimensional vector space and $\varphi : V \rightarrow W$ is a linear transformation, then*

$$\dim(\ker(\varphi)) + \dim(\text{im}(\varphi)) = \dim(V).$$

$\dim(\text{im}(\varphi))$ is called the rank and $\dim(\ker(\varphi))$ is called the nullity of φ .

Example 1.7 *Consider the matrix A which defines a linear transformation from \mathbb{F}_2^7 to \mathbb{F}_2^3 :*

$$A = \begin{bmatrix} 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 & 1 & 0 & 1 \end{bmatrix}.$$

- $\dim(\text{im}(\varphi)) = 3$.
- $\dim(\ker(\varphi)) = 4$.
- Check that $\ker(\varphi)$ is a code which can recover from one bit of error.
- Check that this is also true for the $(2^k - 1) \times k$ matrix A_k where the i^{th} column is the number i written in binary (with the most significant bit at the top).

This code is known as the Hamming Code and the matrix A is called the parity-check matrix of the code.

2 Eigenvalues and eigenvectors

Definition 2.1 *Let V be a vector space over the field \mathbb{F} and let $\varphi : V \rightarrow V$ be a linear transformation. $\lambda \in \mathbb{F}$ is said to be an eigenvalue of φ if there exists $v \in V \setminus \{0_V\}$ such that $\varphi(v) = \lambda \cdot v$. Such a vector v is called an eigenvector corresponding to the eigenvalue λ . The set of eigenvalues of φ is called its spectrum:*

$$\text{spec}(\varphi) = \{\lambda \mid \lambda \text{ is an eigenvalue of } \varphi\}.$$

Example 2.2 *Consider the following transformations:*

- Differentiation is a linear transformation on the class of infinitely differentiable functions and each function of the form $c \cdot \exp(\lambda x)$ is an eigenvector with eigenvalue λ .
- Consider the transformation $\varphi_{\text{left}} : \mathbb{R}^{\mathbb{N}} \rightarrow \mathbb{R}^{\mathbb{N}}$. Any geometric progression with common ratio r is an eigenvector of φ_{left} with eigenvalue r (and these are the only eigenvectors for this transformation).

Proposition 2.3 Let $U_\lambda = \{v \in V \mid \varphi(v) = \lambda \cdot v\}$. Then for each $\lambda \in \mathbb{F}$, U_λ is a subspace of V .

Note that $U_\lambda = \{0_V\}$ if λ is not an eigenvalue. The dimension of this subspace is called the geometric multiplicity of the eigenvalue λ .

Proposition 2.4 Let $\lambda_1, \dots, \lambda_k$ be distinct eigenvalues of φ with associated eigenvectors v_1, \dots, v_k . Then the set $\{v_1, \dots, v_k\}$ is linearly independent.

Definition 2.5 A transformation $\varphi : V \rightarrow V$ is said to be diagonalizable if there exists a basis of V comprising of eigenvectors of φ .

Exercise 2.6 Recall that $\text{Fib} = \{f \in \mathbb{R}^{\mathbb{N}} \mid f(n) = f(n-1) + f(n-2) \forall n \geq 2\}$. Show that $\varphi_{\text{left}} : \text{Fib} \rightarrow \text{Fib}$ is diagonalizable. Express the sequence by $f(0) = 1, f(1) = 1$ and $f(n) = f(n-1) + f(n-2) \forall n \geq 2$ (known as Fibonacci numbers) as a linear combination of eigenvectors of φ_{left} .