

TTIC 31250: An Introduction to the Theory of Machine Learning

Semi-Supervised Learning

Avrim Blum

05/30/2018

Semi-Supervised Learning

- The main models we have been studying (PAC, mistake-bound) are for supervised learning.
 - Given labeled examples $S = \{(x_i, y_i)\}$, try to learn a good prediction rule.
- Unfortunately, labeled data is often expensive.
- On the other hand, unlabeled data is often plentiful and cheap.
 - Documents, images, OCR, web-pages, protein sequences,
...

Can we use unlabeled data to help?

Semi-Supervised Learning

- Two scenarios: active learning and semi-supervised learning.
 - **Active learning:** have ability to ask for labels of unlabeled points of interest.
 - Can you do better than just ask for labels on random subset?
 - **Semi-supervised learning:** no querying. Just have lots of additional unlabeled data.
 - Will look today at SSL. This is the most puzzling one since unclear what unlabeled data can do for you.

Semi-Supervised Learning

Given a set L of labeled data and set U of unlabeled data. Can we use U to help?

- What can the unlabeled data possibly do for us?
- Abstract high-level answer we will get to is:
 - Going back to "Occam's razor", unlabeled data can help us improve our notion of what is simpler than what, by identifying regularities that appear in the data.
- But first:
 - Discuss several methods that have been developed for using unlabeled data to help.
 - Then will give an extension of PAC model to make sense of what's going on.

Plan for today

Methods:

- Co-training
- Transductive SVM
- Graph-based methods

Model:

- Augmented PAC model for SSL.

There's also a book "Semi-supervised learning" on the topic.

Co-training

[B&Mitchell'98] motivated by [Yarowsky'95]

Yarowsky's Problem & Idea:

- Some words have multiple meanings (e.g., "plant"). Want to identify which meaning was intended in any given instance.
- Standard approach: learn function from local context to desired meaning, using labeled data. "...nuclear power plant generated..."
- Idea: use fact that in most documents, multiple uses have **same** meaning. Use to transfer confident predictions over.

Co-training

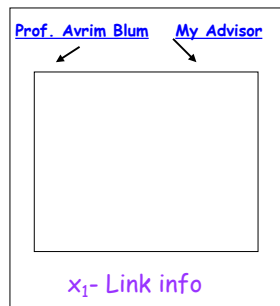
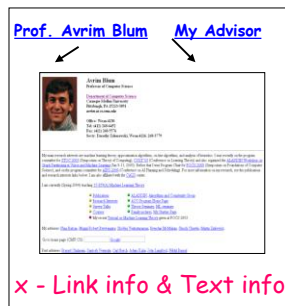
Actually, many problems have a similar characteristic.

- Examples x can be written in two parts (x_1, x_2).
- Either part alone is in principle sufficient to produce a good classifier.
- E.g., speech+video, image and context, web page contents and links.
- So if confident about label for x_1 , can use to impute label for x_2 , and vice versa. Use each classifier to help train the other.

"Multi-view learning"

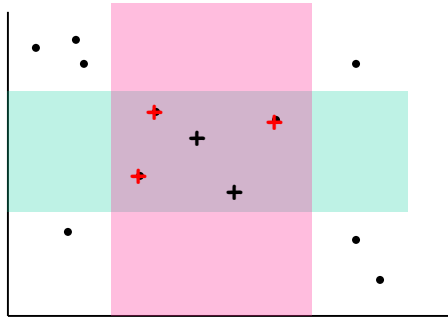
Example: classifying webpages

- Co-training: Agreement between two parts
 - examples contain two **sets of features**, i.e. an example is $x = \langle x_1, x_2 \rangle$ and the belief is that the two parts of the example are sufficient and consistent, i.e. $\exists c_1, c_2$ such that $c_1(x_1) = c_2(x_2) = c(x)$



Example: intervals

Suppose $x_1 \in \mathbb{R}, x_2 \in \mathbb{R}$. $c_1 = [a_1, b_1], c_2 = [a_2, b_2]$



Co-Training Theorems

- [BM98] if x_1, x_2 are independent given the label: $D = p(D_1^+ \times D_2^+) + (1-p)(D_1^- \times D_2^-)$, and if C is SQ-learnable (or from random class noise), then can learn from an initial "weakly-useful" h_1 plus unlabeled data.
- Def: h is weakly-useful if

$$\Pr[h(x)=1 | c(x)=1] > \Pr[h(x)=1 | c(x)=0] + \epsilon.$$

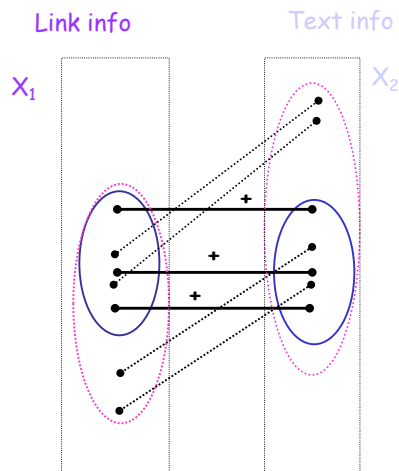
 (same as weak hyp if target c is balanced)
- E.g., say "syllabus" appears on 1/3 of course pages but only 1/6 of non-course pages.
- Idea: use as a noisy label of other view. (helpful trick: balance data so observed labels are 50/50)

Co-Training Theorems

- [BB] in some cases (e.g., LTFs), you can use this to learn from a single labeled example.
 - Pick random hyperplane and boost (using above).
 - Repeat process multiple times.
 - Get 4 kinds of hyps: {close to c , close to $\neg c$, close to 1, close to 0}
 - Just need one labeled example to choose right one.
- [BBY] if don't want to assume independence, and C is learnable from positive data only, then suffices for D^+ to have *expansion*.

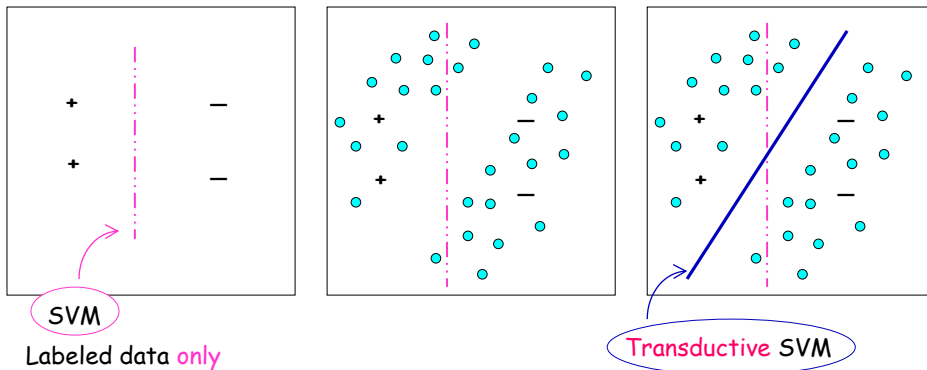
Co-Training and expansion

Want initial sample to expand to full set of positives after limited number of iterations.



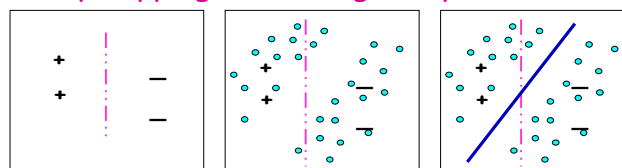
Transductive SVM [Joachims99]

- Suppose we believe target separator goes through **low** density regions of the space/**large margin**.
- Aim for separator with large margin wrt labeled **and unlabeled** data. (L+U)



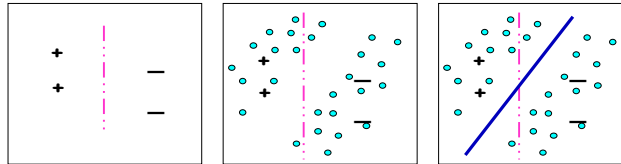
Transductive SVM [Joachims99]

- Suppose we believe target separator goes through **low** density regions of the space/**large margin**.
- Aim for separator with large margin wrt labeled **and unlabeled** data. (L+U)
- Unfortunately, optimization problem is now NP-hard. Algorithm instead does local optimization.
 - Start with large margin over labeled data. Induces labels on U.
 - Then try flipping labels in greedy fashion.



Transductive SVM [Joachims99]

- Suppose we believe target separator goes through **low** density regions of the space/**large margin**.
- Aim for separator with large margin wrt labeled **and unlabeled** data. (L+U)
- Unfortunately, optimization problem is now NP-hard. Algorithm instead does local optimization.
 - Also, work on polynomial-time approximation algorithms. ("furthest hyperplane problem")

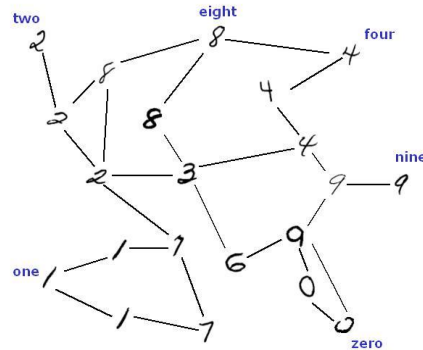


Graph-based methods

- Suppose we believe that very similar examples probably have the same label.
- If you have a lot of labeled data, this suggests a Nearest-Neighbor type of alg.
- If you have a lot of **unlabeled** data, suggests a graph-based method.

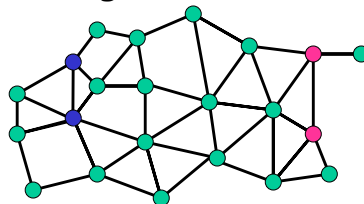
Graph-based methods

- Transductive approach. (Given $L + U$, output predictions on U).
- Construct a graph with edges between very similar examples.
- Solve for:
 - Minimum cut
 - Minimum "soft-cut" [ZhuGhahramaniLafferty]
 - Spectral partitioning



Graph-based methods

- Suppose just two labels: 0 & 1.
- Solve for labels $f(x)$ for unlabeled examples x to minimize:
 - $\sum_{e=(u,v)} |f(u)-f(v)|$ [soln = minimum cut]
 - $\sum_{e=(u,v)} (f(u)-f(v))^2$ [soln = electric potentials]
- In case of min-cut, can use counting/VC-dim results to get confidence bounds.
 - VC-dimension of class of cuts of size k is $O(k/\lambda_{min})$, where λ_{min} is the minimum nontrivial cut in the graph. [Kleinberg]



How can we think about these approaches to using unlabeled data in a PAC-style model?

PAC-SSL Model [BB]

- **Augment** the notion of a **concept class** C with a notion of **compatibility** χ between a concept and the data distribution.
 - "learn C " becomes "learn (C, χ) " (i.e. learn class C under compatibility notion χ)
- Express relationships that one hopes the target function and underlying distribution will possess.
- **Idea**: use unlabeled data & the belief that the target is compatible to reduce C down to just {the highly compatible functions in C }.
 - Or, order the functions in C by compatibility.

PAC-SSL Model [BB]

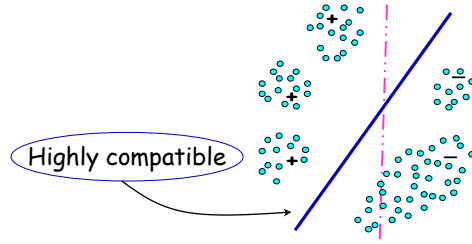
- **Augment** the notion of a **concept class** C with a notion of **compatibility** χ between a concept and the data distribution.
 - "learn C " becomes "learn (C, χ) " (i.e. learn class C under compatibility notion χ)
- To do this, need to be able to estimate compatibility of h with D from unlabeled data.
- Require that the degree of compatibility be something that can be **estimated** from a **finite** sample.

PAC-SSL Model [BB]

- **Augment** the notion of a **concept class** C with a notion of **compatibility** χ between a concept and the data distribution.
 - "learn C " becomes "learn (C, χ) " (i.e. learn class C under compatibility notion χ)
- Require χ to be an **expectation over individual examples**:
 - $\chi(h, D) = E_{x \sim D}[\chi(h, x)]$ = compatibility of h with D ,
 $\chi(h, x) \in [0, 1]$
 - $\text{err}_{\text{unl}}(h) = 1 - \chi(h, D)$ = incompatibility of h with D
(unlabeled error rate of h)

Margins, Compatibility

- **Margins:** belief is that should exist a large margin separator.

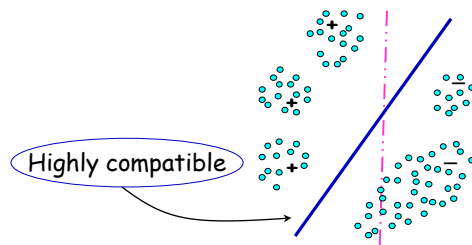


- **Incompatibility of h and D** (unlabeled error rate of h): the probability mass within distance γ of h .
- Can be written as an expectation over individual examples $\chi(h, D) = E_{x \sim D}[\chi(h, x)]$ where:
 - $\chi(h, x) = 0$ if $\text{dist}(x, h) < \gamma$
 - $\chi(h, x) = 1$ if $\text{dist}(x, h) > \gamma$

$$\text{err}_{\text{unl}}(h) = \Pr_{x \sim D} [\text{dist}(x, h) < \gamma]$$

Margins, Compatibility

- **Margins:** belief is that should exist a large margin separator.



- If do not want to commit to γ in advance, define $\chi(h, x)$ to be a smooth function of $\text{dist}(x, h)$, e.g.:

$$\chi(h, x) = 1 - e^{\left[-\frac{\text{dist}(x, h)}{2\sigma^2}\right]} \quad \text{err}_{\text{unl}}(h) = E_{x \sim D} \left[e^{\left[-\frac{\text{dist}(x, h)}{2\sigma^2}\right]} \right]$$

- **Illegal** notion of compatibility: the **largest** γ s.t. D has probability mass **exactly** zero within distance γ of h .

Co-Training, Compatibility

- **Co-training**: examples come as pairs $\langle x_1, x_2 \rangle$ and the goal is to learn a pair of functions $\langle h_1, h_2 \rangle$
- **Hope** is that the two parts of the example are consistent.

- **Legal** (and **natural**) notion of compatibility:

- the compatibility of $\langle h_1, h_2 \rangle$ and D :

$$\Pr_{\langle x_1, x_2 \rangle \in D} [h_1(x_1) = h_2(x_2)]$$

- can be written as an expectation over examples:

$$\chi(\langle h_1, h_2 \rangle, \langle x_1, x_2 \rangle) = 1 \text{ if } h_1(x_1) = h_2(x_2)$$

$$\chi(\langle h_1, h_2 \rangle, \langle x_1, x_2 \rangle) = 0 \text{ if } h_1(x_1) \neq h_2(x_2)$$

Sample Complexity - Uniform convergence bounds

Finite Hypothesis Spaces, Doubly Realizable Case

- Define $C_{D,\chi}(\epsilon) = \{h \text{ in } C : \text{err}_{\text{unl}}(h) < \epsilon\}$.

Theorem

If we see

$$m_u \geq \frac{1}{\epsilon} \left[\ln |C| + \ln \frac{2}{\delta} \right]$$

unlabeled examples and

$$m_l \geq \frac{1}{\epsilon} \left[\ln |C_{D,\chi}(\epsilon)| + \ln \frac{2}{\delta} \right]$$

labeled examples, then with probability $\geq 1 - \delta$, all $h \in C$ with $e\hat{r}r(h) = 0$ and $e\hat{r}r_{\text{unl}}(h) = 0$ have $\text{err}(h) \leq \epsilon$.

- **Bound the # of labeled examples as a measure of the helpfulness of D with respect to χ**
 - a helpful distribution is one in which $C_{D,\chi}(\epsilon)$ is small

Example

- Every variable is a positive indicator or negative indicator. No example has both kinds.
 - Algorithm: create graph on variables. Put an edge between two variables if any example has both of them.
 - Bad distribution: uniform over unit-vectors $\{e_i\}$.
 - Good distribution:
 - Small number of connected components.
 - Both classes have good "expansion".

More Generally

- Want algorithm that runs in poly time using samples poly in respective bounds.
- E.g., can think of:
 - $\ln|C|$ as # bits to describe target without knowing D ,
 - $\ln|C_{D,\chi}(\varepsilon)|$ as number of bits to describe target knowing a good approx to D ,under assumption that target has low unlabeled error rate.
- Can get analogous sample-complexity bounds when target is not perfectly compatible.

Infinite hypothesis spaces / VC-dimension

Infinite Hypothesis Spaces

Assume $\chi(h, x)$ in $\{0, 1\}$ and $\chi(C) = \{\chi_h : h \in C\}$ where $\chi_h(x) = \chi(h, x)$.

Two issues:

1. If we want uniform convergence of **unlabeled** error rates (all $h \in C$ have $|\widehat{err}_{unl}(h) - err_{unl}(h)| \leq \epsilon$) then we need unlabeled sample size to be large as a function of VC-dimension of $\chi(C)$.
2. For "size" of highly-compatible set, the max number of ways of splitting m points is not a good measure. Instead:

$C[m, D]$: **expected** # of splits of m points **from** D with concepts in C .

Infinite hypothesis spaces / VC-dimension

Infinite Hypothesis Spaces

Assume $\chi(h, x)$ in $\{0, 1\}$ and $\chi(C) = \{\chi_h : h \in C\}$ where $\chi_h(x) = \chi(h, x)$.

$C[m, D]$ - **expected** # of splits of m points **from** D with concepts in C .

Theorem

$$m_u = O\left(\frac{VCdim(\chi(C))}{\epsilon^2} \log \frac{1}{\epsilon} + \frac{1}{\epsilon^2} \log \frac{2}{\delta}\right)$$

unlabeled examples and

$$m_l > \frac{2}{\epsilon} \left[\log(2s) + \log \frac{2}{\delta} \right]$$

labeled examples, where

$$s = C_{D, \chi}(t + 2\epsilon)[2m_l, D]$$

are sufficient so that with probability at least $1 - \delta$, all $h \in C$ with $\widehat{err}(h) = 0$ and $\widehat{err}_{unl}(h) \leq t + \epsilon$ have $err(h) \leq \epsilon$, and furthermore all $h \in C$ have

$$|err_{unl}(h) - \widehat{err}_{unl}(h)| \leq \epsilon$$

Implication: If $err_{unl}(c^*) \leq t$, then with probab. $\geq 1 - \delta$, the $h \in C$ that optimizes both $\widehat{err}(h)$ and $\widehat{err}_{unl}(h)$ has $err(h) \leq \epsilon$.

ϵ -Cover-based bounds

- For algorithms that behave in a **specific** way:
 - **first** use the **unlabeled** data to choose a **representative** set of compatible hypotheses
 - **then** use the **labeled** sample to choose among these

Theorem

If t is an upper bound for $err_{unl}(c^*)$ and p is the size of a minimum ϵ -cover for $C_{D,\chi}(t + 4\epsilon)$, then using

$$m_u = O\left(\frac{VCdim(\chi(C))}{\epsilon^2} \log \frac{1}{\epsilon} + \frac{1}{\epsilon^2} \log \frac{2}{\delta}\right)$$

unlabeled examples and

$$m_l = O\left(\frac{1}{\epsilon} \ln \frac{p}{\delta}\right)$$

labeled examples, we can with probab. $\geq 1 - \delta$ identify a hypothesis which is 10ϵ close to c^* .

- Can result in much better bound than uniform convergence.

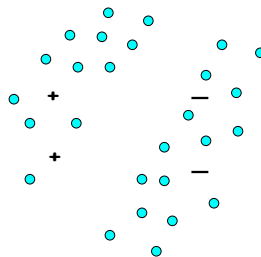
ϵ -Cover-based bounds

- For algorithms that behave in a **specific** way:
 - **first** use the **unlabeled** data to choose a **representative** set of compatible hypotheses
 - **then** use the **labeled** sample to choose among these

E.g., in case of co-training linear separators with independence assumption:

- ϵ -cover of compatible set = $\{0, 1, c^*, \neg c^*\}$

E.g., Transductive SVM when data is in two blobs.



Ways unlabeled data can help in this model

- If the target is highly compatible with D and have enough unlabeled data to estimate χ over all $h \in C$, then can reduce the search space (from C down to just those $h \in C$ whose estimated unlabeled error rate is low).
- By providing an estimate of D , unlabeled data can allow a more refined distribution-specific notion of hypothesis space size (such as the size of the smallest ε -cover).
- If D is nice so that the set of compatible $h \in C$ has a small ε -cover and the elements of the cover are far apart, then can learn from even fewer labeled examples than the $1/\varepsilon$ needed just to verify a good hypothesis.

Some references

- Blum, A., & Mitchell, T. (1998). Combining labeled and unlabeled data with co-training. *COLT 1998*.
- Joachims, T. (1999). Transductive inference for text classification using support vector machines. *ICML 1999* (Vol. 99, pp. 200-209).
- Zhu, X., Ghahramani, Z., & Lafferty, J. (2003). Semi-supervised learning using Gaussian fields and harmonic functions. *ICML 2003* (Vol. 3, pp. 912-919).
- Balcan, M. F., Blum, A., & Yang, K. (2004). Co-training and expansion: Towards bridging theory and practice. *NIPS 2004* (pp. 89-96).
- Chapelle et al., eds. *Semi-supervised learning*. Vol. 2. Cambridge: MIT press, 2006.
- Balcan, M. F., & Blum, A. (2010). A discriminative model for semi-supervised learning. *Journal of the ACM*, 57(3), 19.
- Karnin, Z., Liberty, E., Lovett, S., Schwartz, R., & Weinstein, O. (2012). Unsupervised SVMs: On the complexity of the Furthest Hyperplane Problem. *COLT 2012*.