

TTIC 31250

An Introduction to the Theory of Machine Learning

Learning and Game Theory

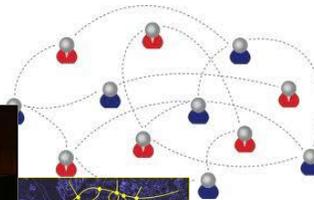
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5/7/18, 5/9/18

- Zero-sum games, Minimax Optimality & Minimax Thm; Connection to Boosting & Regret Minimization
- General-sum games, Nash equilibrium and Correlated equilibrium; Internal/Swap Regret Minimization

Game theory

- Field developed by economists to study social & economic interactions.
 - Wanted to understand why people behave the way they do in different economic situations. Effects of incentives. Rational explanation of behavior.



Game theory

- Field developed by economists to study social & economic interactions.
 - Wanted to understand why people behave the way they do in different economic situations. Effects of incentives. Rational explanation of behavior.
- "Game" = interaction between parties with their own interests. Could be called "interaction theory".
- Important for understanding/improving large systems:
 - Internet routing, social networks, e-commerce
 - Problems like spam etc.

Game Theory: Setting

- Have a collection of participants, or *players*.
- Each has a set of choices, or *strategies* for how to play/ behave.
- Combined behavior results in *payoffs* (satisfaction level) for each player.

Start by talking about important case of
2-player zero-sum games

Consider the following scenario...

- Shooter has a penalty shot. Can choose to shoot left or shoot right.
- Goalie can choose to dive left or dive right.
- If goalie guesses correctly, (s)he saves the day. If not, it's a goooooaaaaaall!
- Vice-versa for shooter.

2-Player Zero-Sum games

- Two players Row and Col. Zero-sum means that what's good for one is bad for the other.
- Game defined by matrix with row for each of Row's options and a column for each of Col's options. Matrix R gives row player's payoffs, C gives column player's payoffs, $R + C = 0$.
- E.g., penalty shot [Matrix R]:

		Left	Right	goalie
shooter	Left	0	1	GOAALL!!!
	Right	1	0	No goal

Minimax-optimal strategies

- Minimax optimal strategy is a (randomized) strategy that has the best guarantee on its expected payoff, over choices of the opponent. [maximizes the minimum]
- I.e., the thing to play if your opponent knows you well.

		Left	Right	goalie
shooter	Left	0	1	GOAALLL!!!
	Right	1	0	No goal

Minimax-optimal strategies

- What are the minimax optimal strategies for this game?

Minimax optimal strategy for shooter is 50/50. Guarantees expected payoff $\geq \frac{1}{2}$ no matter what goalie does.

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		Left	Right	goalie
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	Right	1	0	No goal

Minimax-optimal strategies

- How about for goalie who is weaker on the left?

Minimax optimal for shooter is $(2/3, 1/3)$.

Guarantees expected gain at least $2/3$.

Minimax optimal for goalie is also $(2/3, 1/3)$.

Guarantees expected loss at most $2/3$.

		Left	Right	
shooter	Left	$\frac{1}{2}$	1	goalie
	Right	1	0	

Minimax Theorem (von Neumann 1928)

- Every 2-player zero-sum game has a unique value V .
- Minimax optimal strategy for R guarantees R 's expected gain at least V .
- Minimax optimal strategy for C guarantees C 's expected loss at most V .

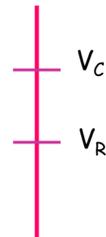
Counterintuitive: Means it doesn't hurt to publish your strategy if both players are optimal. (Borel had proved for symmetric 5×5 but thought was false for larger games)

Minimax-optimal strategies

- Claim: no-regret strategies will do nearly as well or better against any sequence of opponent plays.
 - Do nearly as well as best fixed choice in hindsight.
 - Implies do nearly as well as best distrib in hindsight
 - Implies do nearly as well as minimax optimal!

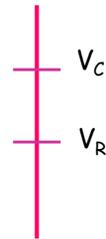
Proof of minimax thm using RWM

- Suppose for contradiction it was false.
- This means some game G has $V_C > V_R$:
 - If Column player commits first, there exists a row that gets the Row player at least V_C .
 - But if Row player has to commit first, the Column player can make him get only V_R .
- Scale matrix so payoffs to row are in $[-1,0]$. Say $V_R = V_C - \delta$.



Proof contd

- Now, consider playing randomized weighted-majority alg as Row, against Col who plays optimally against Row's distrib.
- In T steps, in expectation,
 - Alg gets \geq [best row in hindsight] - $2(T \log n)^{1/2}$
 - $\text{BRiH} \geq T \cdot V_C$ [Best against opponent's empirical distribution]
 - $\text{Alg} \leq T \cdot V_R$ [Each time, opponent knows your randomized strategy]
 - Gap is δT . Contradicts assumption once $\delta T > 2(T \log n)^{1/2}$, or $T > 4 \log(n) / \delta^2$.



What if two regret minimizers play each other?

- Then their time-average strategies must approach minimax optimality.
 1. If Row's time-average is far from minimax, then Col has strategy that in hindsight substantially beats value of game.
 2. So, by Col's no-regret guarantee, Col must substantially beat value of game.
 3. So Row will do substantially worse than value.
 4. Contradicts no-regret guarantee for Row.

Boosting & game theory

- Suppose I have an algorithm A that for any distribution (weighting fn) over a dataset S can produce a rule $h \in H$ that gets $< 45\%$ error.
- Adaboost gives a way to use such an A to get error $\rightarrow 0$ at a good rate, using weighted votes of rules produced.
- How can we see that this is even possible?

Boosting & game theory

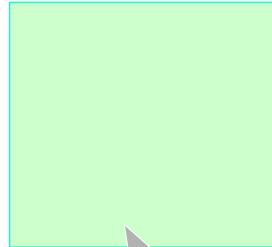
- Let's assume the class H is finite.
- Think of a matrix game where columns indexed by examples in S , rows indexed by h in H .
- $M_{ij} = 1$ if $h_i(x_j)$ is correct, else $M_{ij} = -1$.

Boosting & game theory

- Assume for any D over cols, exists row s.t. $E[\text{payoff}] \geq 0.1$.
- Minimax implies exists a weighting over rows s.t. for every x_i , expected payoff ≥ 0.1 .
- So, $\text{sgn}(\sum_t \alpha_t h_t)$ is correct on all x_i . Weighted vote has L_1 margin at least 0.1.
- AdaBoost gives you a way to get this with only access via weak learner. But this at least implies existence...

$x_1, x_2, x_3, \dots, x_n$

h_1
 h_2
...
 h_m



Entry $ij = 1$ if $h_i(x_j)$ is correct, -1 if incorrect

Internal/Swap Regret and Correlated Equilibria

General-sum games

- In general-sum games, can get win-win and lose-lose situations.
- E.g., "what side of sidewalk to walk on?":

		Left	Right
you	Left	(1,1)	(-1,-1)
	Right	(-1,-1)	(1,1)

person walking towards you



Nash Equilibrium

- A Nash Equilibrium is a stable pair of strategies (could be randomized).
- Stable means that neither player has incentive to deviate on their own.
- E.g., "what side of sidewalk to walk on":

		Left	Right
Left	(1,1)	(-1,-1)	
Right	(-1,-1)	(1,1)	

NE are: both left, both right, or both 50/50.

Existence of NE

- Nash (1950) proved: any general-sum game must have at least one such equilibrium.
 - Might require randomized strategies (called "mixed strategies")
- This also yields minimax thm as a corollary.
 - Pick some NE and let V = value to row player in that equilibrium.
 - Since it's a NE, neither player can do better even knowing the (randomized) strategy their opponent is playing.
 - So, they're each playing minimax optimal.

What if all players minimize regret?

- ♦ In zero-sum games, empirical frequencies quickly approaches minimax optimal.
- ♦ In general-sum games, does behavior quickly (or at all) approach a Nash equilibrium?
 - ♦ After all, a Nash Eq is exactly a set of distributions that are no-regret wrt each other. So if the distributions stabilize, they must converge to a Nash equil.
- ♦ Well, unfortunately, no.

A bad example for general-sum games

- Augmented Shapley game from [Zinkevich04]:
 - First 3 rows/cols are Shapley game (rock / paper / scissors but if both do same action then both lose).
 - 4th action "play foosball" has slight negative if other player is still doing r/p/s but positive if other player does 4th action too.
 - RWM will cycle among first 3 and have no regret, but do worse than only Nash Equilibrium of both playing foosball.
- We didn't really expect this to work given how hard NE can be to find...

A bad example for general-sum games

- [Balcan-Constantin-Mehta12]:
 - Failure to converge even in Rank-1 games (games where $R+C$ has rank 1).
 - Interesting because one can find equilibria efficiently in such games.

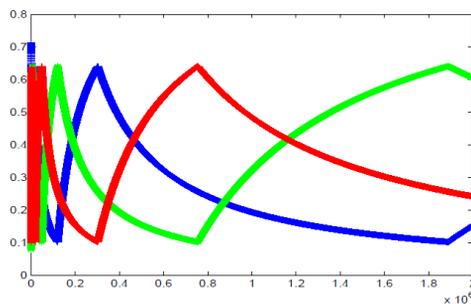


Figure 4. c_i s of symmetric Shapley game with $a = 10$, $b = 1$

What can we say?

- If algorithms minimize "internal" or "swap" regret, then empirical distribution of play approaches *correlated equilibrium*.
 - Foster & Vohra, Hart & Mas-Colell,...
 - Though doesn't imply play is stabilizing.

What are internal/swap regret
and correlated equilibria?

More general forms of regret

1. "best expert" or "external" regret:
 - Given n strategies. Compete with best of them in hindsight.
2. "sleeping expert" or "regret with time-intervals":
 - Given n strategies, k properties. Let S_i be set of days satisfying property i (might overlap). Want to simultaneously achieve low regret over each S_i .
3. "internal" or "swap" regret: like (2), except that $S_i =$ set of days in which we chose strategy i .

Internal/swap-regret

- E.g., each day we pick one stock to buy shares in.
 - Don't want to have regret of the form "every time I bought IBM, I should have bought Microsoft instead".
- Formally, swap regret is wrt optimal function $f:\{1,\dots,n\}\rightarrow\{1,\dots,n\}$ such that every time you played action j , it plays $f(j)$.

Weird... why care?

"Correlated equilibrium"

- Distribution over entries in matrix, such that if a trusted party chooses one at random and tells you your part, you have no incentive to deviate.
- E.g., Shapley game.

	R	P	S
R	-1,-1	-1,1	1,-1
P	1,-1	-1,-1	-1,1
S	-1,1	1,-1	-1,-1

In general-sum games, if all players have low swap-regret, then empirical distribution of play is apx correlated equilibrium.

Connection

- If all parties run a low swap regret algorithm, then empirical distribution of play is an apx correlated equilibrium.
 - Correlator chooses random time $t \in \{1, 2, \dots, T\}$. Tells each player to play the action j they played in time t (but does not reveal value of t).
 - Expected incentive to deviate: $\sum_j \Pr(j)(\text{Regret} | j) = \text{swap-regret of algorithm}$
 - So, this suggests correlated equilibria may be natural things to see in multi-agent systems where individuals are optimizing for themselves

Correlated vs Coarse-correlated Eq

In both cases: a distribution over entries in the matrix. Think of a third party choosing from this distr and telling you your part as "advice".

"Correlated equilibrium"

- You have no incentive to deviate, even after seeing what the advice is.

"Coarse-Correlated equilibrium"

- If only choice is to see and follow, or not to see at all, would prefer the former.

Low external-regret \Rightarrow apx coarse correlated equilib.

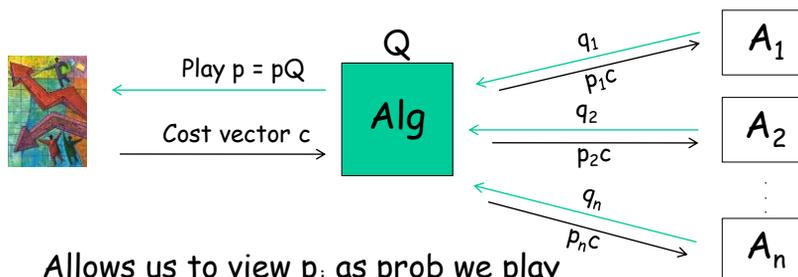
Internal/swap-regret, contd

Algorithms for achieving low regret of this form:

- Foster & Vohra, Hart & Mas-Colell, Fudenberg & Levine.
- Will present method of [BM05] showing how to convert any "best expert" algorithm into one achieving low swap regret.
- Unfortunately, #steps to achieve low swap regret is $O(n \log n)$ rather than $O(\log n)$.

Can convert any "best expert" algorithm A into one achieving low swap regret. Idea:

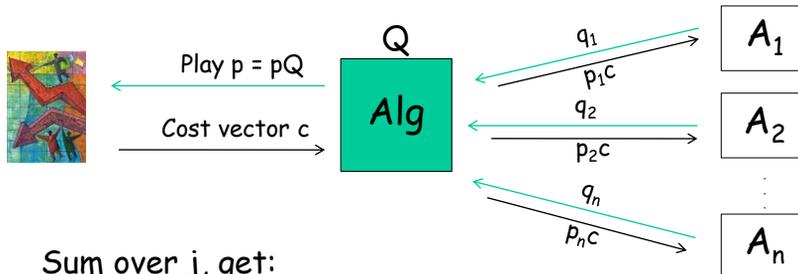
- Instantiate one copy A_j responsible for expected regret over times we play j .



- Allows us to view p_j as prob we play action j , or as prob we play alg A_j .
- Give A_j feedback of p_jc .
- A_j guarantees $\sum_t (p_j^t c^t) \cdot q_j^t \leq \min_i \sum_t p_j^t c_i^t + [\text{regret term}]$
- Write as: $\sum_t p_j^t (q_j^t \cdot c^t) \leq \min_i \sum_t p_j^t c_i^t + [\text{regret term}]$

Can convert any "best expert" algorithm A into one achieving low swap regret. Idea:

- Instantiate one copy A_j responsible for expected regret over times we play j .



- Sum over j , get:

$$\sum_t p^t Q^t c^t \leq \sum_j \min_i \sum_t p_j^t c_i^t + n[\text{regret term}]$$

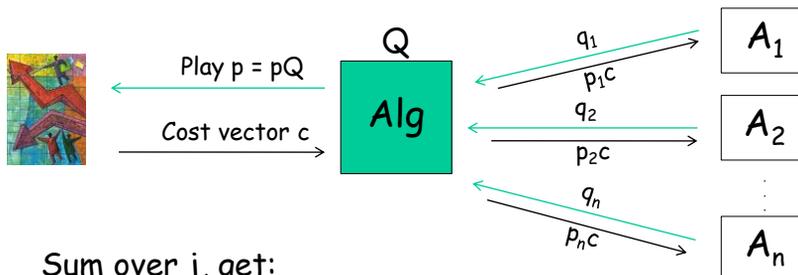
Our total cost

For each j , can move our prob to its own $i=f(j)$

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- Get swap-regret at most n times orig external regret.