## Lecture 1: September 28, 2021

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The primary goal of this course is to collect a set of basic mathematical tools which are often useful in various areas of computer science. We will mostly focus on various applications of linear algebra and probability. Please see the course webpage for a more detailed list of topics.
The course will be evaluated on the basis of the following:

- Homeworks: 60\% (five homeworks contributing $12 \%$ each)
- Midterm: 15\%
- Final: 25\%

We will spend 3-4 of lectures reviewing some of the basic concepts of linear algebra before we move on to some of the applications.
Here's a couple of problems to think about if you are already familiar with the contents of this lecture. These are from the excellent book "Thirty Three Miniatures" by Jiří Matoušek [Mat10], both which I highly recommend for many more fun applications of Linear Algebra (you can find a link in the "resources" section of the course webpage.)

Problem 0.1 Show that a rectangle with sides 1 and $\sqrt{2}$ cannot be tiled with a finite number of non-overlapping squares. In fact, you can try to prove that this is the case when $\sqrt{2}$ is replaced by any irrational number $x$.

Problem 0.2 Let $K_{n}$ denote the complete graph on the vertex set $[n]=\{1, \ldots, n\}$. Also, for disjoint $S, T \subseteq[n]$, let $K_{S, T}$ denote the complete bipartite graph with the edge set

$$
E_{S, T}=\{\{i, j\} \mid i \in S, j \in T\} .
$$

Show that if $\left(S_{1}, T_{1}\right), \ldots,\left(S_{m}, T_{m}\right)$ are such that each edge of $K_{n}$ is present in exactly one of the graphs $K_{S_{i}, T_{i}}$, then $m \geq n-1$. Is this tight?

## 1 Fields

A field, often denoted by $\mathbb{F}$, is simply a nonempty set with two associated operations + and $\cdot$ mapping $\mathbb{F} \times \mathbb{F} \rightarrow \mathbb{F}$, which satisfy:

- commutativity: $a+b=b+a$ and $a \cdot b=b \cdot a$ for all $a, b \in \mathbb{F}$.
- associativity: $a+(b+c)=(a+b)+c$ and $a \cdot(b \cdot c)=(a \cdot b) \cdot c$ for all $a, b, c \in \mathbb{F}$.
- identity: There exist elements $0_{\mathbb{F}}, 1_{\mathbb{F}} \in \mathbb{F}$ such that $a+0_{\mathbb{F}}=a$ and $a \cdot 1_{\mathbb{F}}=a$ for all $a \in \mathbb{F}$.
- inverse: For every $a \in \mathbb{F}$, there exists an element $(-a) \in \mathbb{F}$ such that $a+(-a)=0_{\mathbb{F}}$. For every $a \in \mathbb{F} \backslash\left\{0_{\mathbb{F}}\right\}$, there exists $a^{-1} \in \mathbb{F}$ such that $a \cdot a^{-1}=1_{\mathbb{F}}$.
- distributivity of multiplication over addition: $a \cdot(b+c)=a \cdot b+a \cdot c$ for all $a, b, c \in$ F.

Example 1.1 $Q, \mathbb{R}$ and $\mathbb{C}$ with the usual definitions of addition and multiplication over these fields.

Example 1.2 Consider defining addition and multiplication on $\mathrm{Q}^{2}$ as

$$
(a, b)+(c, d)=(a+c, b+d) \quad \text { and } \quad(a, b) \cdot(c, d)=(a c+b d, a d+b c) .
$$

These operations do not define a field. While various properties of addition are indeed satisfied, inverses may not always exist for multiplication as defined above. Check that the multiplicative identity needs to be $(1,0)$ but then the element $(1,-1)$ has no multiplicative inverse.
However, for any prime $p$, the following operations do define a field

$$
(a, b)+(c, d)=(a+c, b+d) \quad \text { and } \quad(a, b) \cdot(c, d)=(a c+p b d, a d+b c) .
$$

This is equivalent to taking $\mathbb{F}=\{a+b \sqrt{p} \mid a, b \in \mathbb{Q}\}$ with the same notion of addition and multiplication as for real numbers. Alternatively, one can also define a field by taking ( $a, b$ ). $(c, d)=(a c-b d, a d+b c)(w h y ?)$

Example 1.3 For any prime $p$, the set $\mathbb{F}_{p}=\{0,1, \ldots, p-1\}$ (also denoted as $G F(p)$ ) is a field with addition and multiplication defined modulo $p$. Also, check that defining addition and multiplication modulo a composite number (say modulo 6) does not give a field.

Exercise 1.4 Show that the set $\{a+b \sqrt[3]{2}+c \sqrt[3]{4} \mid a, b, c \in \mathbb{Q}\}$ is a field.

## 2 Vector Spaces

A vector space $V$ over a field $\mathbb{F}$ is a nonempty set with two associated operations + : $V \times V \rightarrow V$ (vector addition) and $\cdot: \mathbb{F} \times V \rightarrow V$ (scalar multiplication) which satisfy:

- commutatitivity of addition: $v+w=w+v$ for all $v, w \in V$.
- associativity of addition: $u+(v+w)=(u+v)+w \forall u, v, w \in V$.
- pseudo-associativity of scalar multiplication: $a \cdot(b \cdot v)=(a \cdot b) \cdot v \forall a, b \in \mathbb{F}, v \in V$.
- identity for vector addition: There exists $0_{V} \in V$ such that for all $v \in V, v+0_{V}=v$.
- inverse for vector addition: $\forall v \in V, \exists(-v) \in V$ such that $v+(-v)=0_{V}$.
- distributivity: $a \cdot(v+w)=a \cdot v+a \cdot w$ and $(a+b) \cdot v=a \cdot v+b \cdot v$ for all $a, b \in \mathbb{F}$ and $v, w \in V$.
- identity for scalar multiplication: $1_{\mathbb{F}} \cdot v=v$ for all $v \in V$.

Example 2.1 Any field $\mathbb{F}$ is a vector space over itself.
Example 2.2 $\mathbb{R}$ is a vector space over $\mathbb{Q}$.
Example 2.3 Let $\mathbb{R}[x]$ denote the space of polynomials in one variable $x$, with real coefficients i.e.,

$$
\mathbb{R}[x]:=\left\{\sum_{i=0}^{t} c_{i} \cdot x^{i} \mid t \in \mathbb{N}, c_{0}, \ldots, c_{t} \in \mathbb{R}\right\} .
$$

Then, $\mathbb{R}[x]$ is a vector space over $\mathbb{R}$. Similarly, the space $\mathbb{R}^{\leq d}[x]$ of polynomials with degree at most $d$, defined as

$$
\mathbb{R}^{\leq d}[x]:=\left\{\sum_{i=0}^{t} c_{i} \cdot x^{i} \mid t \in \mathbb{N}, t \leq d, c_{0}, \ldots, c_{t} \in \mathbb{R}\right\}
$$

is also a vector space over $\mathbb{R}$.
Example 2.4 $C([0,1], \mathbb{R})=\{f:[0,1] \rightarrow \mathbb{R} \mid f$ is continuous $\}$ is a vector space over $\mathbb{R}$.
Example 2.5 $\mathrm{Fib}=\left\{f \in \mathbb{R}^{\mathbb{N}} \mid f(n)=f(n-1)+f(n-2) \forall n \geq 2\right\}$ is a vector space over $\mathbb{R}$.
Definition 2.6 (Linear Dependence) $A$ set $S \subseteq V$ is linearly dependent if there exist distinct $v_{1}, \ldots, v_{n} \in S$ and $c_{1}, \ldots, c_{n} \in \mathbb{F}$ not all zero, such that $\sum_{i=1}^{n} c_{i} \cdot v_{i}=0_{V}$. A set which is not linearly dependent is said to be linearly independent. A sum of the form $\sum_{i=1}^{n} c_{i} \cdot v_{i}$ is referred to as a linear combination of the vectors $v_{1}, \ldots, v_{n}$.

Example 2.7 The set $\{1, \sqrt{2}, \sqrt{3}\}$ is linearly independent in the vector space $\mathbb{R}$ over the field $\mathbb{Q}$.

Exercise 2.8 Let $a_{1}, \ldots, a_{n} \in \mathbb{R}$ be distinct and let $g(x)=\prod_{i=1}^{n}\left(x-a_{i}\right)$. Define

$$
f_{i}(x)=\frac{g(x)}{x-a_{i}}=\prod_{j \neq i}\left(x-a_{j}\right),
$$

where we extend the function at point $a_{i}$ by continuity. Prove that $f_{1}, \ldots, f_{n}$ are linearly independent in the vector space $\mathbb{R}[x]$ over the field $\mathbb{R}$.

## 3 Span and Bases

Definition 3.1 Given a set $S \subseteq V$, we define its span as

$$
\operatorname{Span}(S)=\left\{\sum_{i=1}^{n} a_{i} \cdot v_{i} \mid a_{1}, \ldots, a_{n} \in \mathbb{F}, v_{1}, \ldots, v_{n} \in S, n \in \mathbb{N}\right\}
$$

Note that we only include finite linear combinations. Also, since linear combinations of vectors are still in $V$, we have $\operatorname{Span}(S) \subseteq V$. In fact, you can check that Span $(S)$ is also a vector space. Such a subset of $V$, which is also a vector space, is called a subspace of $V$.

Remark 3.2 Note that the definition above and the previous definitions of linear dependence and independence, all involve only finite linear combinations of the elements. Infinite sums cannot be said to be equal to a given element of the vector space without a notion of convergence or distance, which is not necessarily present in an abstract vector space.

Definition 3.3 A set $B$ is said to be a basis for the vector space $V$ if $B$ is linearly independent and Span $(B)=V$.

We will say that a set $B \subseteq V$ is a maximal linearly independent set if $B$ is linearly independent and for all $v \in V \backslash B, B \cup\{v\}$ is linearly dependent. It is often useful to use the following alternate characterization of a basis.

Proposition 3.4 $A$ set $B \subseteq V$ is a basis for $V$ if and only if $B$ is a maximal linearly independent set.

Proof: We will prove the "if" part and leave the other part as an exercise. If $B$ is a maximal linearly independent set, then we already know that it is linearly independent, and only need to show that $\operatorname{Span}(B)=V$. By the maximality property, we have that for all $v \in V \backslash B$, the set $B \cup\{v\}$ is linearly dependent. Thus, for some $n \in \mathbb{N}$, there exist $v_{1}, \ldots, v_{n} \in B \cup\{v\}$ and $c_{1}, \ldots, c_{n} \in \mathbb{F}$ such that $\sum_{i=1}^{n} c_{i} \cdot v_{i}=0_{V}$. Also, $v$ must be one of the vectors $v_{!}, \ldots, v_{n}$ with a non-zero coefficient (otherwise we have a linear dependency in $B$ itself). Thus, $v$ can be written as a linear combination of the other $v_{i} \mathrm{~s}$ and we have $v \in \operatorname{Span}(B)$ for all $v \in V \backslash B$. Since it is also true that $B \subseteq \operatorname{Span}(B)$, we get that $V=\operatorname{Span}(B)$.

## References

[Mat10] Jiří Matoušek, Thirty-three miniatures: Mathematical and algorithmic applications of linear algebra, vol. 53, American Mathematical Soc., 2010. 1

